

Report on the AAPM deep-learning spectral CT Grand Challenge

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Funding information

Office of Extramural Research, National Institutes of Health, Grant/Award Numbers: R01-EB026282, R01-EB023968, R21-CA263660

Abstract

Background: This Special Report summarizes the 2022 AAPM Grand Challenge on Deep-Learning spectral Computed Tomography (DL-spectral CT) image reconstruction.

Purpose: The purpose of the challenge is to develop the most accurate image reconstruction algorithm possible for solving the inverse problem associated with a fast kilovolt switching dual-energy CT scan using a three tissue-map decomposition. Participants could choose to use a deep-learning (DL), iterative, or a hybrid approach.

Methods: The challenge is based on a 2D breast CT simulation, where the simulated breast phantom consists of three tissue maps: adipose, fibroglandular, and calcification distributions. The phantom specification is stochastic so that multiple realizations can be generated for DL approaches. A dual-energy scan is simulated where the x-ray source potential of successive views alternates between 50 and 80 kilovolts (kV). A total of 512 views are generated, yielding 256 views for each source voltage. We generate 50 and 80 kV images by use of filtered back-projection (FBP) on negative logarithm processed transmission data. For participants who develop a DL approach, 1000 cases are available. Each case consists of the three 512×512 tissue maps, 50 and 80-kV transmission data sets and their corresponding FBP images. The goal of the DL network would then be to predict the material maps from either the transmission data, FBP images, or a combination of the two. For participants developing a physics-based approach, all of the required modeling parameters are made available: geometry, spectra, and tissue attenuation curves. The provided information also allows for hybrid approaches where physics is exploited as well as information about the scanned object derived from the 1000 training cases. Final testing is performed by computation of root-mean-square error (RMSE) for predictions on the tissue maps from 100 new cases.

Results: Test phase submission were received from 18 research groups. Of the 18 submissions, 17 were results obtained with algorithms that involved DL. Only the second place finishing team developed a physics-based image reconstruction algorithm. Both the winning and second place teams had highly accurate results where the RMSE was nearly zero to single floating point precision. Results from the top 10 also achieved a high degree of accuracy; and as a result, this special report outlines the methodology developed by each of these groups.

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Conclusions: The DL-spectral CT challenge successfully established a forum for developing image reconstruction algorithms that address an important inverse problem relevant for spectral CT.

KEYWORDS

adaptive radiotherapy, deformable image registration, quality assurance

1 | INTRODUCTION

This Special Report summarizes the American Association of Physicists in Medicine (AAPM) sponsored 2022 Grand Challenge on deep-learning (DL) for spectral computed tomography (CT) image reconstruction, DL-spectral CT. The DL-spectral CT Grand Challenge is motivated by the interest in addressing inverse problems in imaging using DL, and DL-spectral CT follows and builds off of the 2021 AAPM Grand Challenge on DL for sparse-view CT image reconstruction, DL-sparse-view CT.¹ While DL has been heavily investigated for image reconstruction/restoration problems,² there has not been much work reported on the accuracy of DL methodology for inversion of the imaging models that underpin tomographic image reconstruction. These challenges provide a forum in which to test DL methodology on inverse problems relevant to CT image reconstruction. Before explaining the design of the 2022 DL-spectral CT challenge, we briefly recapitulate the design and results of the 2021 DL-sparse-view CT challenge. The sparse-view challenge was based on our paper with Lorente and Brankov,³ where we attempted to use previously published work on convolutional neural networks (CNNs) to solve a sparse-view CT image reconstruction problem. In this article, we were not able to show a numerical solution of the sparse-view CT solution. The sparse-view CT inverse problem is known to have a solution by using iterative image reconstruction exploiting gradient sparsity as demonstrated in Sidky et al.³ Because there was a published solution to this sparse-view problem, the participants of the DL-sparse-view challenge did not have full knowledge of the projection model as this would have allowed them to simply reconstruct the images using the gradient-sparsity exploiting algorithm. The participants had to rely on the 4000-case training set to devise an accurate DL-based image reconstruction algorithm. In last year's challenge, 25 competing teams submitted their predictions for the testing set, which consisted of 100 cases. The winning team, Robust-and-stable, achieved highly accurate image reconstruction on each of the test cases and the numerical error was small enough that it was not visible within the display gray scale window appropriate for the test phantom. The Robust-and-stable team published their methodology in the Proceedings of the 39th International Conference on Machine Learning⁴ and they have also made code available. For the 2022 DL-spectral CT challenge, we constructed a simulation

based on a hypothetical dual-energy breast CT system. The goal is to recover three tissue maps, adipose, fibroglandular, and calcification distributions, from simulated noiseless dual-energy transmission data. Unlike the sparse-view problem of the previous challenge, this particular inverse problem does not have a published solution, and accordingly, we provided complete knowledge of the forward model. A training set of 1000 cases for this challenge enabled DL approaches. With the forward model available, participants could also develop iterative algorithms that solve the physical imaging model; or hybrid physics- and DL-based approaches could be devised. Because the provided data are generated from the ground truth images without any inconsistencies, it is in principle possible to recover the exact ground truth tissue maps. Accordingly, the metric used for rating performance is the root-mean-square error (RMSE) of the predicted test case tissue maps from the ground truth. Because this particular inverse problem has not been solved, we did not know in advance if the RMSE could in fact be driven to zero.

A total of 18 teams submitted their predictions for the 100 cases of the test phase for DL-spectral CT. As with last year's challenge, the participating teams came up with highly innovative algorithms that included DL-based, physics-based, and hybrid approaches. There was, again, a good spread in RMSE scores and the winning/runner-up teams achieved accurate tissue map recovery up to six/five decimal places. Because the accuracy level of the results was high and the methodology so varied, we report briefly on the methodology of the top 10 performing teams. The details of the DL-spectral CT challenge are presented in Section 2, where the physical imaging model and logistics of the DL-spectral CT challenge are discussed. The results of the challenge are shown in Section 3 along with overview descriptions of the top 10 algorithms. Finally, a discussion that summarizes what was learned about the three tissue-map recovery problem in dual-energy CT is given in Section 4.

2 | METHODS

As with DL sparse-view CT, the present DL-spectral CT challenge is focused on solving an inverse problem relevant for CT imaging; see Section IIA of the DL sparse-view CT challenge report for background on Inverse Problem theory.¹ The basic idea is to set up a

simulation where the data are generated from a physical model of the scanner using computer simulated images, and then to see if the test images can be recovered accurately from perfect knowledge of the data, that is, no noise. For DL-spectral CT, we provide the complete physical model for the dual-energy fast kilovolt-switching scan configuration. The breast phantom is composed of three tissue maps modeling adipose, fibroglandular, and calcification distributions. For participants interested in developing a DL-based algorithm, we also provide a training set of 1000 cases, where each case consists of a breast phantom realization, dual-energy CT transmission data, and filtered back-projection (FBP) reconstructed low and high kilovolt images. Participants aim to estimate the three tissue maps based on the provided transmission data and/or the kilovolt images. In this section, we cover the details of the spectral CT model, the evaluation of the results, and the logistics of the challenge.

2.1 | Fast kilovolt-switching dual-energy CT simulation

The breast CT simulation models the transmission data for dual-energy CT as

$$I_w = \int s_w(E) \exp[-\mu_a(E)P_w x_a - \mu_f(E)P_w x_f - \mu_c(E)P_w x_c] dE, \quad (1)$$

where I_w is the normalized transmission data for the kilovolt setting indexed by $w \in \{\text{low, high}\}$; $s_w(E)$ is the normalized spectral response for kilovolt setting w , that is,

$$\int s_w(E) dE = 1;$$

$\mu_a(E)$, $\mu_f(E)$, and $\mu_c(E)$ are the linear attenuation coefficients for adipose, fibroglandular, and calcification tissues, respectively, at x-ray energy E ; P_w represents x-ray projection and the index w is included because the projection matrix is different for high and low kilovolt settings; and x_a , x_f , and x_c are the spatial distributions of adipose, fibroglandular, and calcification tissues, respectively. By using normalized spectra, the transmission through air is also normalized to 1. For the dual-energy setup, we select the settings to be 50 and 80 kV for the low and high energy scans, respectively. The x-ray source spectra are generated using the SpekPy software described in Bujila et al.⁵ The $s_w(E)$ functions shown in Figure 1 are obtained by multiplying the x-ray source spectra by E , assuming an ideal energy-integrating detector, and normalizing the resulting distribution. The linear attenuation coefficients shown in Figure 2 are obtained from the mass attenuation coefficients available from Hubbell and Seltzer⁶ multiplied by the density of the respective tissue type. For the fibroglandular and adipose tissues, the attenu-

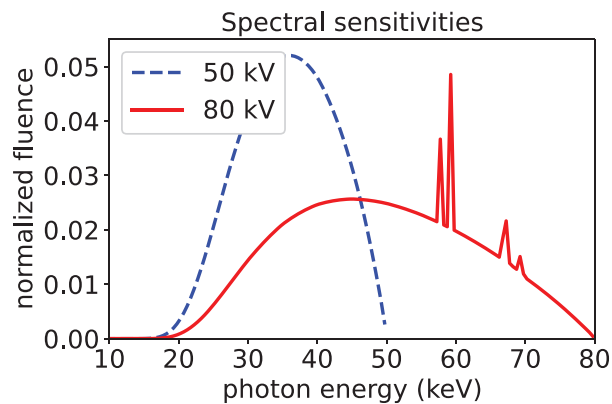


FIGURE 1 Normalized spectral sensitivities for low and high kilovolt transmission data. The spectra are generated modeling a Tungsten anode and 1.6-mm Aluminum filtration. Energy weighting is included in order to model an energy-integrating detector.

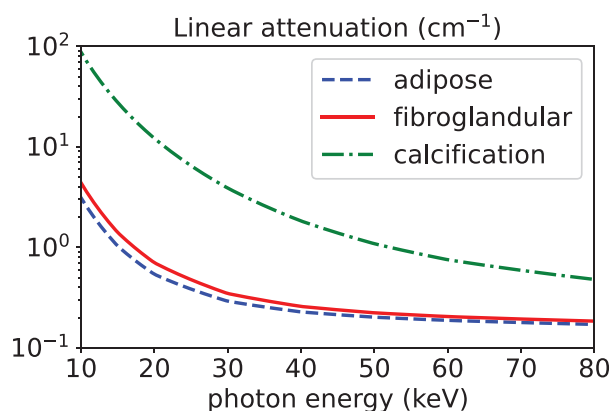


FIGURE 2 Linear attenuation curves for the three tissues used in the generating the challenge transmission data.

ation coefficients are derived from ICRU report no. 44,⁷ and the calcification is taken to be hydroxyapatite.⁸

For the generation of the tissue sinograms, $P_w x$, we implement a standard line-intersection model for the x-ray transform of a discrete image. The images x are pixelized on a 512×512 grid with physical area (18 cm^2). The x-ray source follows a circular trajectory with a radius of 50 cm and centered on the middle of the image. The source-to-detector-center distance is 100 cm, and the detector is modeled as a linear array, which is the exact length needed to capture rays passing through the largest inscribed circle of the image array. The low and high kilovolt sinograms are comprised of 256 equally distributed views over a 360° scan and the projections are sampled on a 1024-pixel detector. The low and high kilovolt sinograms are differentiated by the fact that their projection view angles are shifted by a half of the angular sampling interval, thereby simulating a 512-view acquisition where the kilovolt is switched for consecutive views.

As with the 2021 DL-sparse-view CT challenge, a stochastic breast model is used to generate multiple phantoms for training, validating, and testing purposes in DL-spectral CT. The method for generating the

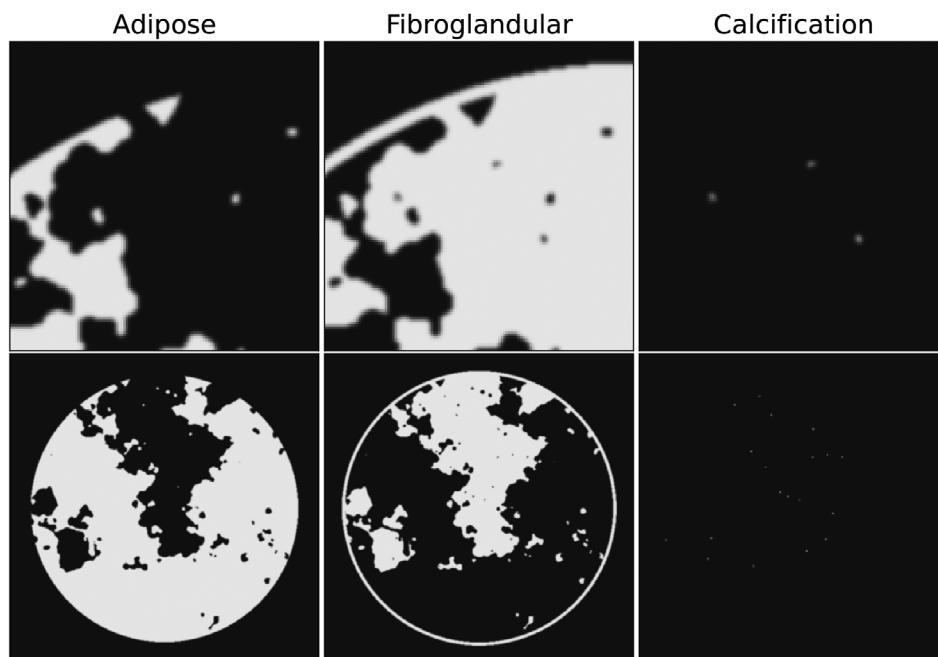


FIGURE 3 One realization of the breast phantom model. Shown are the three tissue maps with a blow-up of an ROI in the top row and the complete image in the bottom row. The gray scale range is $[-0.1, 1.1]$. The voxel values, themselves, range from 0 to 1, indicating the fill fraction of the particular tissue in the pixels.

fibroglandular tissue spatial distributions is based on work by Reiser and Nishikawa.^{3,9} The skin line is included with the fibroglandular tissue map and the skin line is taken to be a fixed circular ring. To create this tissue map, pixels that are within the fibroglandular region or skin line are set to 1 and all other pixels are set to zero. This map is then smoothed with a Gaussian kernel to create a smooth transition at the edges of the distributions. The adipose tissue map is specified by subtracting the fibroglandular map from a uniform disk within the skin line. A calcification map with smoothed specks of random shapes is placed only within the fibroglandular regions. This calcification map is subtracted from the fibroglandular tissue map. All tissue maps range from zero to one, indicating the volume fraction within each pixel. The sum of all the tissue maps is exactly equal to one in the region within the circular skin line. An example realization of the breast phantom tissue map distributions is shown in Figure 3.

The transmission data are generated from the breast phantom tissue maps by Equation (1); no additional inconsistency, such as noise, is introduced into the transmission data. For participants who want to pursue an image-to-image approach images are generated from I_{low} and I_{high} by applying FBP to the dual-energy sinograms, which are obtained by

$$g_w = -\log I_w, \quad (2)$$

where I_w is defined in Equation (1). The resulting low and high dual-energy images corresponding to the realization shown Figure 3 is shown in Figure 4. Algorithms

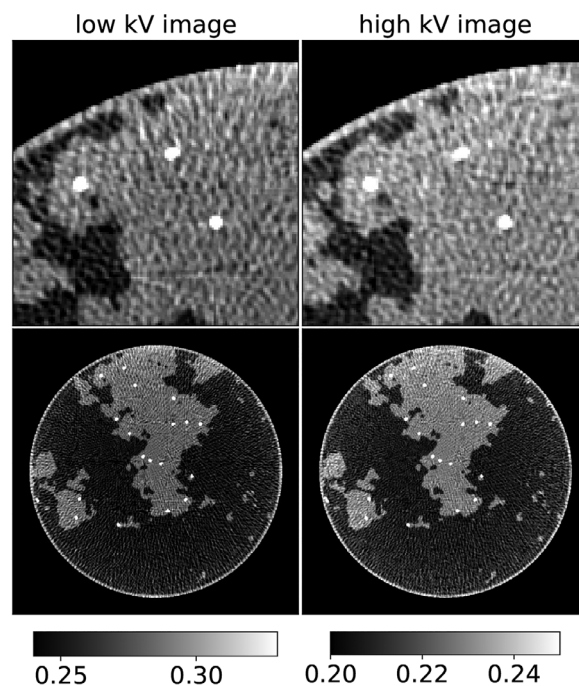


FIGURE 4 Dual energy images reconstructed by applying FBP to the dual-energy sinograms. The ROI shown in the top row is the same as the ROI shown in Figure 3. The gray scale in cm^{-1} is indicated in the column titles. Note the cupping artifact, where the image center is slightly darker than the outer rim of the test phantom. This cupping, a.k.a. beam-hardening, is due the fact that the logarithm processing does not exactly invert the exponentiation in the transmission model when the spectra are broad. The streak artifacts originate from the discrete angular sampling where only 256 views are taken for each of the kilovolt settings. FBP, filtered back-projection.

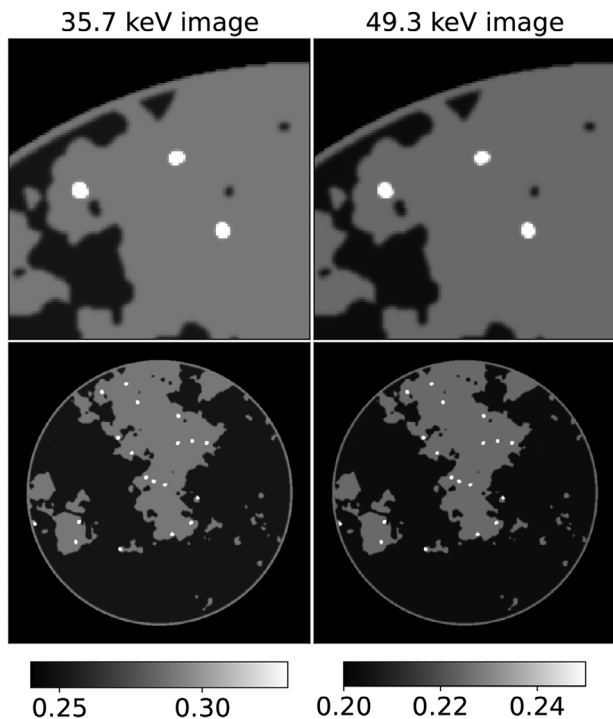


FIGURE 5 Virtual monochromatic images corresponding to the dual-energy images shown in Figure 4 using the same gray scales. The left/right columns show the VMIs for 35.7/49.3-keV x-ray photons, which are the mean energies of the low/high kilovolt spectra. VMIs, virtual monochromatic images.

developed in the DL-spectral CT challenge can use the transmission data, dual-energy sinograms, or the dual-energy images as inputs to their algorithm.

An important concept in dual-energy imaging is what is known as the virtual monochromatic image (VMI), and VMIs play a role in this challenge because many of the participants estimate VMIs as an intermediate step on the way to estimating the tissue maps. The VMI is a hypothetical construct, where the spectral response is a Dirac delta function

$$s_w^{\text{VMI}}(E) = \delta(E - E_w).$$

Substituting this spectrum model into Equation (1), the VM sinograms can be found using Equation (2)

$$g_w^{\text{VMI}} = P_w x^{\text{VMI}}(E_w),$$

which is the projection of the VMI

$$x^{\text{VMI}}(E_w) = \mu_a(E_w)x_a + \mu_f(E_w)x_f + \mu_c(E_w)x_c. \quad (3)$$

For illustration, the VMIs, shown in Figure 5, are formed by performing a weighted sum of the tissue maps in Figure 3. The advantage of using the VMIs as an intermediate estimation step is that going from the

dual-energy images in Figure 4 to the VMIs in Figure 5 amounts to removal of image artifacts for which there are many U-net-based CNNs published in the literature.

2.2 | Challenge logistics and scoring metrics

The provided training set consisted of 1000 cases, where each case included the three ground truth tissue maps, dual-energy transmission data, and dual-energy FBP images. Participants were tasked with developing an algorithm that can generate the tissue maps from the dual-energy transmission data or FBP images. There was no restriction on the type of algorithm; algorithms could be iterative, neural-network-based, or a hybrid of the two. Also provided were python codes for generating transmission data from the tissue maps and the FBP images from the dual-energy transmission data. In this way, all participants had access to exact knowledge of the dual-energy CT modeling.

The scoring of the submissions use two RMSE-based metrics. The RMSE averaged over all 100 test case predictions of the tissue maps is the primary means of determining the ranking of submissions

$$s_1 = \frac{1}{100} \sum_{i=1}^{100} \sqrt{\frac{\|t_i - r_i\|_2^2}{3n}},$$

where r and t are the triplet image sets of reconstructed and ground truth tissue maps, respectively; i is the test case index; $n = 512^2$ is the number of pixels in a single tissue map image. In case of a tie-breaking situation and for further characterization of the results, we also computed a worst-case ROI RMSE

$$s_2 = \max_{i,c} \sqrt{\frac{\|b_c^T(t_i - r_i)\|_2^2}{3m}},$$

where b_c is the image of an indicator function for a 25×25 pixel ROI centered on coordinates c , and $m = 625$ is the number of pixels in the test ROI for each tissue map. The location for the test ROI is the same for each of the tissue map images. For this competition, it was not clear from the outset that exact recovery was possible, which would be indicated if $s_1 = s_2 = 0$. As of yet, there is no published image reconstruction algorithm that is capable of solving the posed inverse problem.

As with the previous 2021 DL sparse-view CT challenge, the 2022 DL-spectral CT challenge¹⁰ is hosted by the MedICI Platform (see <https://www.medicichallenges.org/>). The MedICI team hosts the challenge data, which is accessible by sftp protocol, and they also provided the initial implementation of the challenge

on CodaLab (see https://github.com/codalab/codalab-competitions/wiki/Project_About_CodaLab). Using CodaLab, the MedICI team created the challenge and leaderboard format, set up the submission checking, and created the python plugins that perform the computation of the challenge metrics. The CodaLab challenge page for DL-spectral CT ran the competition in automated fashion dividing the competition into three phases: training, validation, and testing.

The training data were released on March 17th to start off the 2022 DL-spectral CT challenge. On March 31st, 10 new cases were made available, where only the dual-energy FBP images and transmission data were released. Participants could submit their predicted tissue maps for these 10 cases as many times as they wished, and a leaderboard marked the progress of the competition by showing the ranking of the scores for these 10 cases. For this validation phase, participants were not required to submit their results to the leaderboard. The final test phase of the competition ran from May 17th to May 31st. For this phase, 100 new cases were generated and the ground truth tissue maps were withheld. Participants could only submit results for evaluation three times, and the scores for each test phase submission were automatically registered on the leaderboard. In this way, all participants were aware of the best scores submitted. In total, 18 teams submitted test phase results and a total of 39 submissions were made, with 14 submissions sent on the last day of the competition, and five in the last hour. The eventual second place result was submitted at 10:20 pm on the last day, and the winning result came in at 11:24 pm. With the late lead change and volume of last day submissions, the drama of the competition was high!

3 | RESULTS

Submissions for the challenge were received from 18 teams, and all teams except for one developed an image reconstruction algorithm that exploits DL in some form. Scatter plots of the final test phase results appear in Figures 6 and 7. For the leading results, the worst-case ROI RMSE tracks with the average RMSE, which is the metric used for ranking the submitted tissue map predictions. Generally speaking, the performance level for the challenge participants was excellent; the natural scale of this reconstruction problem is zero to one, which are the extreme ranges of the tissue filling fraction for the image pixels. The obtained RMSE values are substantially below one, and the leading results approach numerical exactness at the level of four-byte, that is, single precision, floating point arithmetic. The scatter plot in Figure 6 reveals a healthy spread of scores, and the worst-case ROI RMSE is generally an order of magnitude larger than the corresponding mean RMSE as might be expected. Due to the large dynamic range in

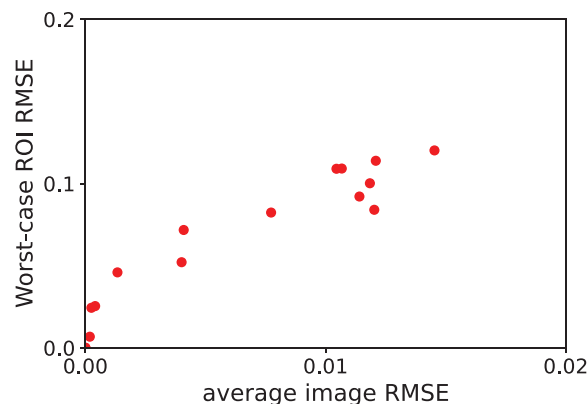


FIGURE 6 Scatter plot of test phase results with average RMSE s_1 on the x-axis and worst-case ROI RMSE s_2 on the y-axis.

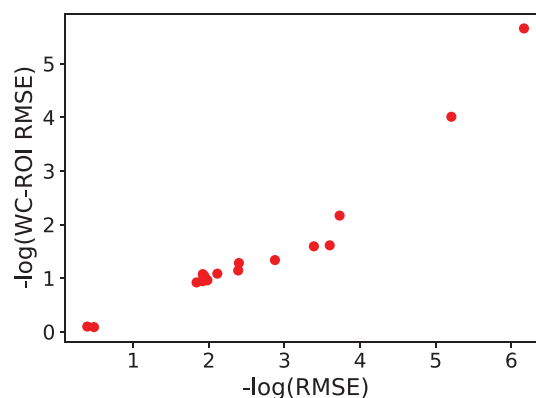


FIGURE 7 Scatter plot of the same test phase results shown in Figure 6 except that the RMSE results are plotted after processing with the negative base-10 logarithm, that is, the x- and y-axes are $-\log_{10} s_1$ and $-\log_{10} s_2$, respectively. In this way, the top performers, which appear in the upper right corner of the plot, are more clearly differentiated.

scores, the two leading results appear at the origin of this plot. To focus on the leading results, in Figure 7, we also show the same scoring data using the negative base-10 logarithm of the RMSE values. The degree of the prediction accuracy of the top two performers becomes clear in this plot. The spread in mean RMSE values allowed unambiguous ranking, nevertheless we also provide the worst-case ROI RMSE values to demonstrate the high level of accuracy in the tissue map predictions. The top 10 teams are listed in Table 1, where the numerical scores are also shown. A full listing of all results are available on the DL-spectral CT challenge website.

One of the more surprising results of the DL-spectral CT challenge is the variety of approaches taken by the challenge participants, and the fact that highly accurate results were obtained with vastly different approaches. The original plan for this challenge report was to highlight the top five algorithms, but the number of high-quality submissions at the test phase forced us to reconsider this plan. We highlight the top 10 performers,

TABLE 1 Top 10 participating teams and their scores.

Username/team	RMSE (s_1)	Worst-case RMSE (s_2)
GenwaiMa/GM_CNU	6.80×10^{-7}	2.20×10^{-6}
huxiaoyu090/iTORCH	6.21×10^{-6}	9.77×10^{-5}
kimhs369/MIR	1.87×10^{-4}	6.81×10^{-3}
WashUDEAM	2.52×10^{-4}	2.44×10^{-2}
dhlee91	4.08×10^{-4}	2.54×10^{-2}
jaspernikamp/DCPT+Navrit	1.34×10^{-3}	4.60×10^{-2}
Duke_QIAL	4.01×10^{-3}	5.21×10^{-2}
leekunpeng/BME_NUC	4.10×10^{-3}	7.18×10^{-2}
flutexu	7.73×10^{-3}	8.24×10^{-2}
Z-VCT	1.04×10^{-2}	1.09×10^{-1}

First place is at the top of the list. For viewing all results, please visit the DL spectral CT challenge website: <https://dl-sparse-view-ct-challenge.eastus.cloudapp.azure.com/competitions/3>.

and we also acknowledge that drawing the line at the top 10 is rather arbitrary.

The algorithms developed by the top 10 participating teams are briefly summarized, and the individual teams are encouraged to publish full presentation of their algorithms. The team membership and institutions are listed. The e-mail address for the contact member is also provided. With each algorithm description, images of the tissue map worst-case ROI are shown. The worst-case ROI images are not shown for the second and first place teams, since there is no visually discernible error in their tissue map predictions.

3.1 | Tenth place

Team Z-VCT uses a combined CNN-based and iterative approach. Their algorithm consists of three major components. The first step seeks to obtain dual-energy images with reduced artifacts from the dual-energy sinograms. For this stage, the SART algorithm is implemented using nonlocal means (NLM) regularization, thereby mitigating the streak artifacts seen in the provided FBP-based dual-energy images. The second stage is composed of two neural networks, the first of which converts the two dual-energy images into an estimate of the three tissue maps. The second network refines this estimate using a standard U-Net. The final, third stage exploits the provided dual-energy physics information with a nonlinear algebraic iterative algorithm, where the tissue maps estimated from the second stage are used to initialize the iteration, in this way, the final tissue map estimates are made consistent with the provided dual-energy transmission data. Team Z-VCT members are Yizhong Wang (wyzwys0101@163.com) and Ailong Cai; both members are from the Information Engineering University in Zhengzhou, China.

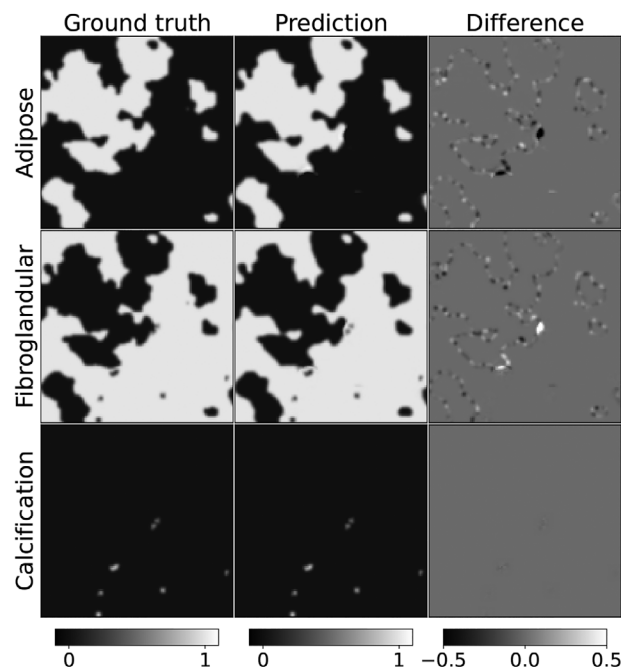


FIGURE 8 Worst-case ROI for the 10th place team. The worst-case ROI is a 25×25 pixel region with the maximum discrepancy, over 100 test images, between the true and predicted tissue maps. For better image context, the shown ROI is expanded 125×125 pixels centered on the worst-case ROI.

The worst-case ROI for this algorithm is shown in Figure 8. The tissue map predictions for this algorithm are visually very accurate; only with guidance from the difference image is it possible to observe small discrepancies in the ground truth and predicted ROI images. The difference images reveal that the largest errors are located at the tissue borders, mainly for the adipose and fibroglandular maps, and that the errors in these two maps are anticorrelated. The form of these errors likely result from the fact that the tissue maps have fractional values at the borders and the fact that the adipose and fibroglandular linear attenuation coefficients have quite similar energy dependences as seen in Figure 2.

3.2 | Ninth place

The algorithm developed by team flutexu involves a two-stage processing chain where the dual-energy sinograms are reconstructed into dual-energy images, which are subsequently fed into a neural network to provide estimates of the tissue maps. The first stage uses an iterative update inspired by the winning team of the 2021 DL sparse-view CT challenge,⁴ where the images are updated based on FBP applied to the difference between the dual-energy sinograms and their estimate derived from the current iterate of the tissue maps. The dual-energy FBP images, provided in the challenge, are used to initialize this iteration. The resulting

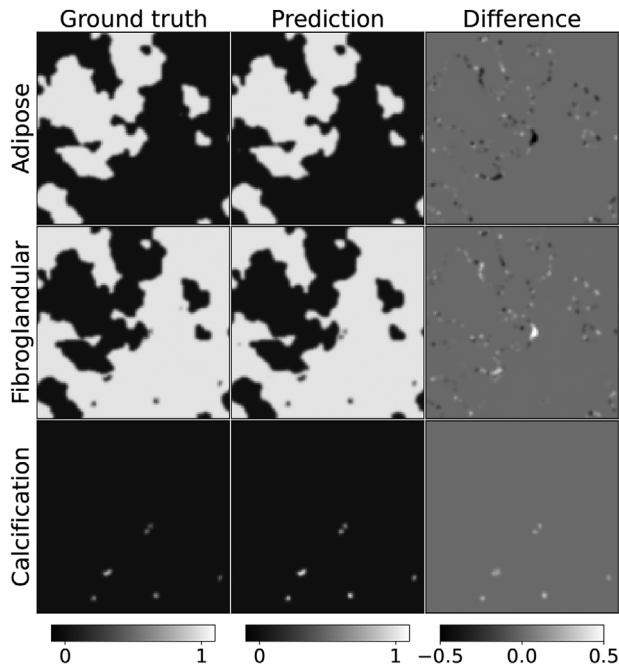


FIGURE 9 Worst-case ROI for the ninth place team. See Figure 8 for description of ROI image specification.

images of the iterative update are fed into a U-Net CNN to provide the estimate of the tissue maps. The free parameters of both stages are trained simultaneously using the provided training cases. This algorithm does exploit the knowledge of the system geometry in the first stage, but the provided dual-energy physics model is not explicitly used. Team flutexu members are Di Xu (DiXu@mednet.ucla.edu) and Ke Sheng; both members are from the Department of Radiation Oncology at the University of California Los Angeles, Los Angeles, California, USA.

The worst-case ROI for this algorithm is shown in Figure 9. Interestingly, the same ROI as that of Figure 8 yielded the worst-case ROI for this algorithm. In fact, this same ROI proved to be the most problematic for many of the other top 10 performing algorithms. Similar observations can be made about the error distributions of this algorithm as with the previous one. One notable difference is that the error in the calcification map is visible and, therefore, of similar amplitude as the error in the other two tissue maps. For the previous result, the error was mainly occurring in the adipose and fibroglandular tissue maps.

3.3 | Eighth place

Team BME_NUC developed an algorithm that they call the intelligent dual-domain network (iDD-Net). The iDD-Net algorithm has two CNNs, the first of which takes as input the dual-energy sinograms and it estimates a fully sampled sinogram for each of the tissue maps. In

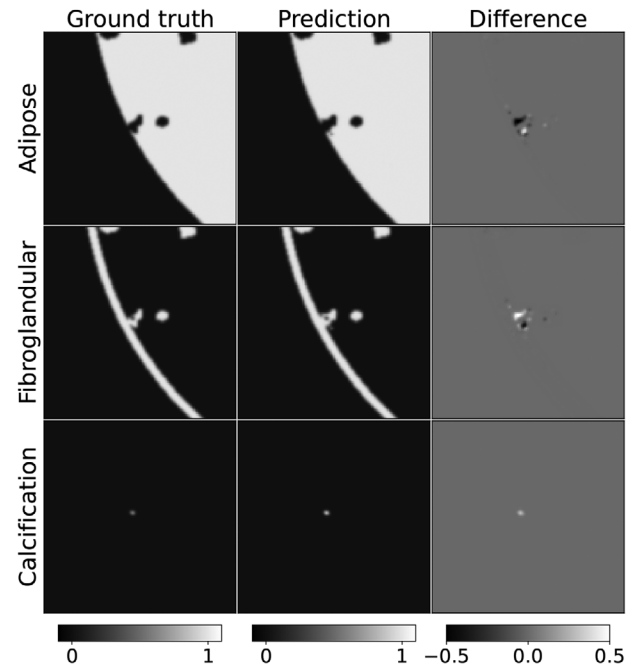


FIGURE 10 Worst-case ROI for the eighth place team. See Figure 8 for description of ROI image specification.

this way, the transformation from dual-energy data to tissue maps is happening in the sinogram domain—a unique feature among the top 10 performing algorithms. The tissue sinograms are back-projected into the image domain, then fed into another CNN to obtain the final tissue map estimates. The complete iDD-Net is trained end-to-end. The only physical parameters of the dual-energy set-up used in training iDD-Net are the geometric parameters needed for the back-projection. Team BME_NUC members are Kunpeng Li (leekunpeng@hotmail.com), Pengcheng Zhang, Yi Liu, and Zhiguo Gui; all members are from the Shanxi Provincial Key Laboratory for Biomedical Imaging and Big Data, North University of China, Taiyuan, China.

The worst-case ROI for this algorithm is shown in Figure 10. For this algorithm, an ROI on the edge of the test phantom yields the worst-case ROI. The error for this ROI is very localized, as opposed to being distributed along the borders of the adipose and fibroglandular tissue maps. Anticorrelation is still observed in the two soft-tissue maps, and an error of comparable amplitude is seen in the calcification map.

3.4 | Seventh place

Team Duke_QIAL developed a four-stage algorithm involving (1) estimation of beam-hardening corrected low and high kilovolt images, (2) a U-net for estimating tissue maps from the dual-energy images, (3) refinement by iterative image reconstruction, and (4) a second pass with a U-net. The first-stage beam hardening correction

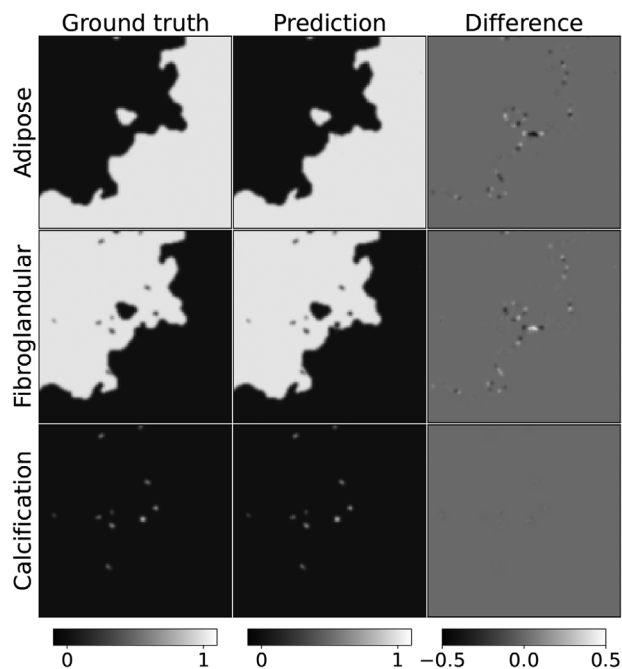


FIGURE 11 Worst-case ROI for the seventh place team. See Figure 8 for description of ROI image specification.

uses the provided spectral response data to fit a second-order polynomial that relates the dual-energy sinograms to sinograms consistent with the projection of VMIs at effective energies for both low and high kilovolt settings. These monochromatic sinograms are processed with algebraic reconstruction to reduce the under-sampling artifacts. In the second stage, a U-net is trained to convert the two VMIs to the three tissue maps; the tissue sum constraint and object support are also enforced at this stage. The third stage runs a single iteration of this team's own spectral CT image reconstruction algorithm¹¹ to update the VMIs and to obtain their corresponding residuals. The final stage involves processing with a U-net similar to the one trained in the second stage; the difference is that the previous U-net takes two VMIs as inputs while the final U-net takes four inputs, VMIs together with their residuals. For both U-nets, thresholding is used to set values within 0.5% of 0 or 1 to exactly 0 or 1. Team Duke_QIAL members are Rohan Nadkarni, Darin Clark, and Cristian Badea (Cristian.Badea@duke.edu), and all members are from the Quantitative Imaging and Analysis Lab, Department of Radiology, Duke University Medical Center, Durham, North Carolina, USA.

The worst-case ROI for this algorithm is shown in Figure 11. The shown ROI is unique among all of the worst-case ROIs shown for the top 10 performing algorithms. The distribution of tissue map errors is concentrated in the middle of the soft-tissue ROI images, but there is also some visible discrepancy along the edges of the soft-tissue maps. Again, the soft-tissue map error is anticorrelated.

3.5 | Sixth place

Team DCPT+Navrit developed a U-net that takes three inputs from which the three tissue maps are predicted. The inputs are the low kilovolt image, the high kilovolt image, and their difference. The dual-energy images used for the U-net are generated from this team's own FBP implementation where they implemented a Hann filter instead of the ramp filter used for generating the dual-energy images in the challenge data set. The U-net is pretrained using ideal, artifact-free VMIs, which are obtained by fitting the FBP-generated dual-energy images with linear combinations of the tissue maps in the training set. After training the U-net on these ideal dual-energy image inputs, transfer learning is used to subsequently adjust the U-net weights by training on the FBP-generated dual-energy image inputs. This algorithm had the best performance among all algorithms that did not explicitly use the given physical spectral model, in Equation (1), that relates the tissue maps to the dual-energy transmission data. Team DCPT+Navrit members are Zixiang Wei, Imaiyan Chitra Ragupathy, Jintao Ren, Navrit Bal, Kristoffer Moos, Mathis Ersted Rasmussen, and Jasper Nijkamp (jaspersnijkamp@clin.au.dk). All members, except Navrit Bal, are from the Department of Clinical Medicine Aarhus University and Danish Center for Particle Therapy, Aarhus University Hospital, Aarhus, Denmark. Navrit Bal is from the Department of Detector Research and Development, National Institute for Subatomic Physics—NIKHEF, Amsterdam, the Netherlands.

The worst-case ROI for this algorithm is shown in Figure 12. This same ROI was the worst confounder for the 10th and ninth place finishers; the error distribution is confined to the soft-tissues and spatially it is quite localized. Anticorrelation in the soft tissues is observed.

3.6 | Fifth place

Team dhlee91 developed an unrolled iterative image reconstruction approach,² where subnetworks having the same structure are repeatedly used for a fixed number of iterations and both data consistency steps and regularization steps are replaced with CNNs. The particular iterative algorithm adopted for the network structure was the primal-dual hybrid gradient algorithm¹² and regularization was performed in both the sinogram-domain and image-domain. The algorithm takes the dual-energy sinograms as input and solves for the three tissue maps. Team dhlee91 had only one member, Donghyeon Lee (dlee258@jhmi.edu) from the Department of Radiology and Radiological Science, Johns Hopkins University School of Medicine, Baltimore, Maryland, USA.

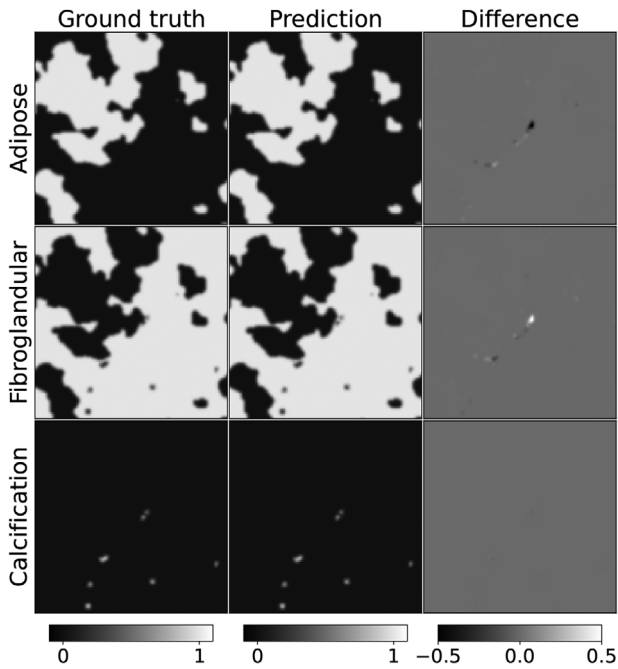


FIGURE 12 Worst-case ROI for the sixth place team. See Figure 8 for description of ROI image specification.

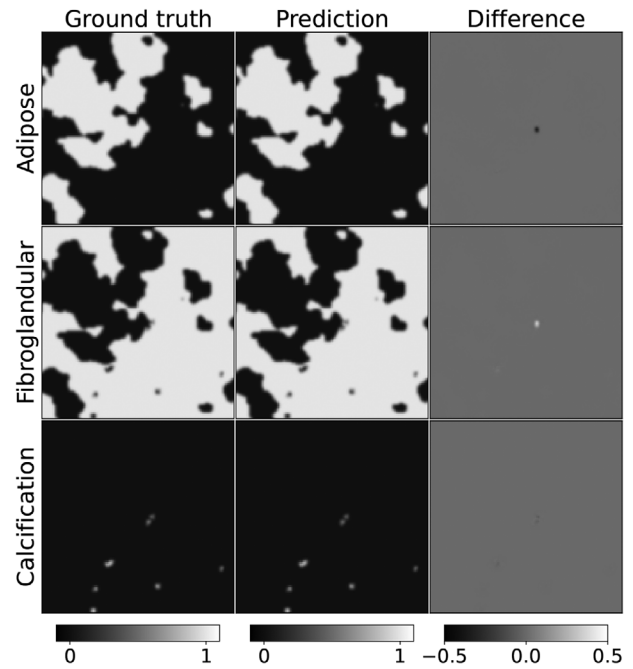


FIGURE 14 Worst-case ROI for the fourth place team. See Figure 8 for description of ROI image specification.

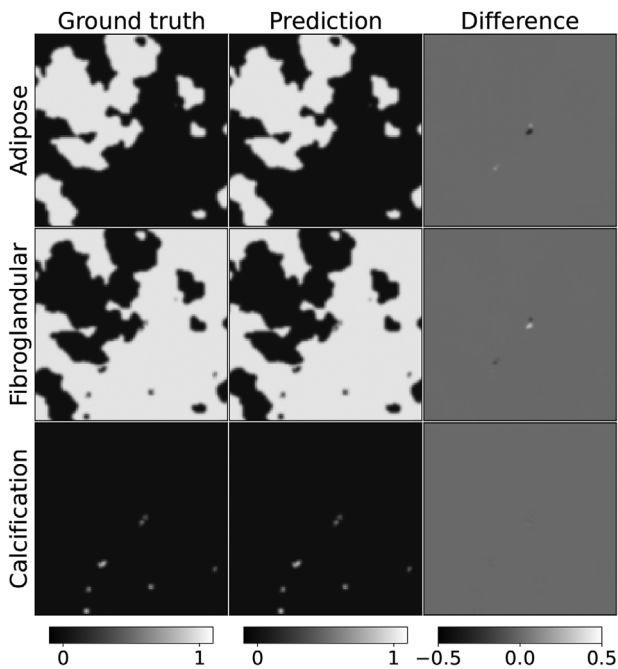


FIGURE 13 Worst-case ROI for the fifth place team. See Figure 8 for description of ROI image specification.

The worst-case ROI for this algorithm is shown in Figure 13. The error distribution is similar to that of the sixth place finisher, shown in Figure 12, except that the visible error is confined to fewer pixels.

3.7 | Fourth place

Team WashUDEAM developed a two-stage image reconstruction algorithm. The first stage is a one-step iterative algorithm that they call dual-energy alternating minimization (DEAM), and which is based on a published algorithms from the same group.^{13,14} In the implementation of DEAM, two of the three tissues are selected as basis materials, and the basis maps are solved directly from the dual-energy transmission data using the given model in Equation (1). In a second stage, a U-net is trained to estimate the three tissue maps from six inputs derived from DEAM. The six inputs are obtained from DEAM by selecting all combinations of two tissues as basis materials, resulting in three possibilities. Each of the three runs of DEAM yields two basis maps for a total six basis maps that are fed into the U-net. In the U-net implementation, the estimated tissue maps are constrained to values in the interval $[0,1]$. Team WashUDEAM members are Tao Ge (getao@wustl.edu), Maria Medrano, Joseph A. O'Sullivan, and all members are from the Department of Electrical and Systems Engineering, Washington University in St. Louis, St. Louis, USA.

The worst-case ROI for this algorithm is shown in Figure 14. The error distribution is similar to that of the fifth and sixth place finisher, shown in Figures 12 and 13, except that the visible error is confined to an even smaller grouping of pixels.

3.8 | Third place

The algorithm developed by team MIR employs four U-nets and enforces data consistency through a simultaneous algebraic reconstruction technique (SART) iteration. The first network estimates the sum of tissue maps from the dual-energy FBP images. For the DL-spectral CT challenge, this network is trivial, because the sum of all tissue maps is the same for all cases, a uniform disk. If, however, this was not the case, training this network becomes a nontrivial and important step. The second U-net estimates a calcification support map, where any pixel that contains some amount of calcium is set to one. The calcium support map is used in the formulation of the SART algorithm. The third U-net estimates calcium and adipose tissue maps from the dual-energy FBP images. The fibroglandular tissue map can be estimated from the difference of the estimated tissue sum map and the sum of adipose and calcification maps. With an accurate initial estimate of all tissue maps, team MIR linearized the transmission model in Equation (1) using the initial estimate as an expansion point. From this linearized model, they derive a SART algorithm to refine all of the tissue maps. Team MIR found that convergence of standard SART was slow, so they used the derived calcification support map to help confine the calcification tissue map and they made use of a fourth U-net specifically designed to reduce the necessary number of iterations. They truncated the SART iteration short of convergence and used the intermediate calcification and adipose map estimates as inputs to the fourth U-net, which then estimates more accurate calcification and adipose maps. Again, the fibroglandular tissue map is obtained by subtracting these maps from the sum of tissue maps. The team MIR members are Hyeongseok Kim (hskim3466@gmail.com) and Seungryong Cho, and both members are from the Korea Advanced Institute of Science and Technology (KAIST), Daejeon, South Korea.

The worst-case ROI for this algorithm is shown in Figure 15. The worst-case ROI is the same one that appeared in the eighth place results shown in Figure 10 except that the error is confined to a few pixels in the center of the images and is barely perceptible in the difference images.

3.9 | Second place

The algorithm developed by team iTORCH is the only one in the top 10 performing entries that did not use CNNs in the data processing. Instead, they used the training data to derive mathematical constraints on the three tissue maps, which they incorporate into an iterative image reconstruction algorithm. The basic iterative algorithm handles the nonlinear model for

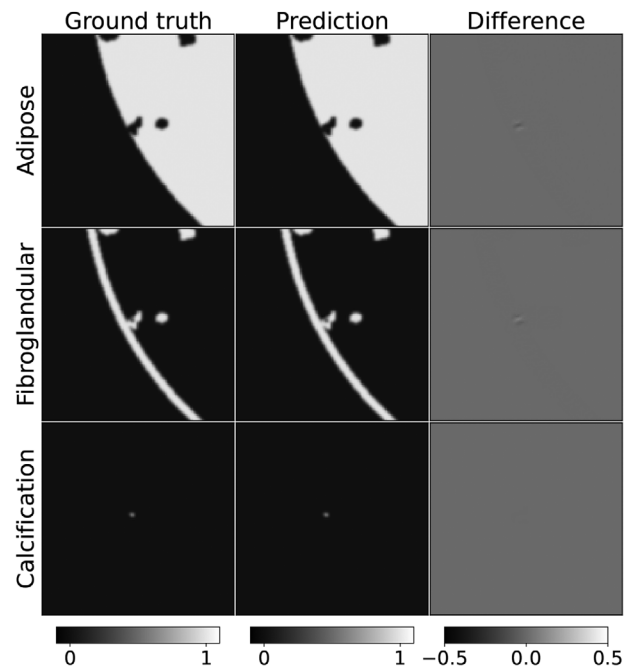


FIGURE 15 Worst-case ROI for the third place team. See Figure 8 for description of ROI image specification.

the transmission data in Equation (1) in a manner similar to the method reported in Chen et al.¹⁵ To optimize the quadratic data fidelity term, the Conjugate Gradients (CG) algorithm is used to obtain dual-energy images with mitigated artifacts. The tissue maps for adipose and fibroglandular tissue are then estimated from these images by least-squares. To augment optimization of the data fidelity term, several regions of the image space are identified using thresholding of the intermediate maps. First, it is noted that the only variable part in the image is a circular region just inside the skin-line. This circular region is separated into “edge” and “nonedge” pixels. For nonedge pixels, tissue maps can only be 1 or 0, and fractional values are confined to edge pixels. Furthermore, it is also noted that the calcification map is spatially sparse and that the sum of the tissue maps within the circular region sum to one. The full algorithm has an outer iteration, where the reconstruction region is bipartitioned into the above-mentioned regions based on the current estimates of the tissue maps. Once these regions are identified, the inner iteration optimizes the data fidelity term with CG, then subsequently enforces the known sum constraint and the binary value constraint for nonedge pixels. The implementation that achieved the second place results only used three outer iterations and variable numbers of inner iterations [10, 30, 30]. Within each inner iteration, CG was run for 200 iterations. The team iTORCH members are Xiaoyu Hu (Xiaoyu.Hu@UTSouthwestern.edu) and Xun Jia, from the Department of Radiation Oncology, University of Texas Southwestern Medical Center, Dallas,

Texas, USA. Xun Jia is presently at the Department of Radiation Oncology and Molecular Radiation Sciences, Johns Hopkins University, Baltimore, Maryland, USA.

The worst-case ROI images are not shown for this algorithm because the maximum pixel discrepancy over all 100 test cases for all three tissue maps is 1.77×10^{-3} and this discrepancy would not be seen in the $[-0.5, 0.5]$ gray scale for the difference images.

3.10 | First place

Team GM_CNU developed the winning algorithm. The algorithm is dual-domain joint learning reconstruction method (JLRM) combined with physical processing for spectral CT (SCT). The overall design of JLRM-SCT includes two main modules: (1) a predecomposition module and (2) a main iterative loop. In each module, both algebraic reconstruction and CNN processing steps are included.

The algebraic method in the predecomposition module uses the extended algebraic reconstruction technique (E-ART)¹⁶ to reconstruct two basis images using adipose and fibroglandular tissues as the basis materials. A CNN is subsequently trained to estimate the three tissue maps from the two basis images, yielding the predecomposition estimate for the JLRM-SCT algorithm. The particular CNN used is based on RED-CNN.¹⁷

In the iterative loop, the tissue map estimates are used to estimate the dual-energy sinograms by a physical modeling network. The difference between these sinograms and the actual sinograms are reconstructed by the standard ART algorithm, yielding residual images. Another CNN is trained that takes five inputs; two are the residual images, and the other three are the current tissue map estimates with attention weighting that highlights edges in the tissue maps. From these five inputs, an increment to the tissue maps is estimated by the trained CNN. This increment is added to the current tissue map estimates, completing the processing within one iteration. For obtaining the challenge results, only two iterations of JLRM-SCT are needed. This team found that they obtained the best results for the CNN in JLRM-SCT loop using residual-to-residual mapping. Also, in the design of their networks, they noted that in order to avoid overfitting, it is important to use CNNs with a small receptive field, that is, small convolution kernels (1 or 3 pixels wide) and avoiding operations that correlate pixels that are distant from each other. The team GM_CNU members are Genwei Ma (magenwei@126.com) and Xing Zhao, and both are at the School of Mathematical Sciences, Capital Normal University, Beijing, China. Dr Zhao is also affiliated with the Shenzhen National Applied Mathematics Center, Southern University of Science and Technology, Shenzhen, China.

The worst-case ROI images for the winning entry are not shown because the maximum pixel discrepancy is an astounding 6.14×10^{-6} !

4 | DISCUSSION AND CONCLUSION

The accuracy of the top 10 algorithms, on predicting the tissue maps of the 100 test cases, range from a mean RMSE at the level of 1% to numerically exact (at the level of single precision floating point computation). We also point out that these impressive results are obtained on an inverse problem in imaging for which there is no published solution. Furthermore, the algorithm development was confined to the 10 week span of the competition; thus, it is likely that the performance of many of the algorithms would improve with further study.

The variety of approaches taken is rather striking. The sixth place team, DCPT+Navrit, achieved the best results of all participants that did not make explicit use of the physical spectral x-ray transmission model. Their algorithm used only the dual-energy images as input. In doing so, they do implicitly use the scan geometry information since it is needed for the FBP algorithm that generates the dual-energy images from dual-energy sinograms. All of the top five algorithms make use of the scan geometry information and the spectral transmission model. Four of the top five algorithms are a hybrid of CNN-based and physics-motivated processing. Interestingly, the second place team, iTORCH, did not use DL in any form; their approach combines known iterative image reconstruction techniques with nonlearning-based image processing. The winning team, GM_CNU, developed a hybrid iterative/CNN approach and they performed numerous studies on optimizing the CNN structure for the posed dual-energy CT inverse problem, achieving truly impressive results.

Many extensions of the DL spectral CT challenge would be interesting for better understanding of the posed dual-energy CT inverse problem. A major issue for learning-based algorithms is generalizability and this takes many forms.

First is the fact that the test set is limited to 100 cases, which is necessary for practical reasons in running the challenge. Mathematically, however, a proposed algorithm for solving an inverse problem has to work all of the time, and not just on 100 cases. To this point, we refer to the 2021 DL sparse-view CT challenge,¹ which had 4000 training cases and 100 test cases. The winning team, Robust-and-stable, tried their algorithm, using the same training dataset, but testing on a much larger 10 000-case dataset in Genzel et al.; their mean RMSE was 6.4×10^{-6} ; the main cluster of individual image RMSE results remained below 1×10^{-5} ; and there was a single extreme outlier at an RMSE of 3×10^{-5} . For the present DL-spectral CT challenge, the training and test sets include 1000 and 100 cases, respectively. It

would be of interest to see how the leading algorithms perform on larger test sets, or, conversely, how do they perform with fewer training cases.

Second, the DL-spectral CT challenge uses test phantoms drawn from a single probabilistic object model, which is loosely based on a 2D breast slice. It would be of interest to try different probabilistic breast slice models, or use models that describe entirely different anatomy with different tissue types. Assuming that the scan configuration is still fast-kilovolt switching dual-energy, the question is how generalizable are the developed algorithms at solving the same inverse problem with a different object model.

Third, one can consider other forms of spectral CT. There are many possible configurations of dual-energy CT. One can also add spectral resolutions with, for example, photon-counting detectors. In addition to changing the spectral resolution, the number of views and view-angle sampling can be varied. These variations in spectral or spatial sampling also vary the imaging inverse problem itself. It would be of interest to know how well the developed algorithms can be adapted to changes in the spectral CT inverse problem.

The 2022 DL-spectral CT challenge problem was designed so that it would be necessary to exploit strong prior information on the scanned objects; there are only two energy windows in the transmission data, but three tissues in the object model. Furthermore, the two soft tissues have very similar linear attenuation curves. The winning team, GM_CNU, developed a hybrid iterative/DL approach, but the second place team, iTORCH, also achieved an extremely high degree of accuracy without DL. Team iTORCH developed an iterative image reconstruction algorithm exploiting “hand-crafted” image processing. Based on the work of the participants, it seems that the best way to use DL for solving the spectral CT inverse problem is in a hybrid algorithm where the full knowledge of the physical model is exploited. Still, it is clear that developing such algorithms is not automatic; despite all of the literature on the use of DL for inverse problems in imaging, no “off-the-shelf” algorithm was used in the challenge. The participants had to work hard to develop their own algorithms to make accurate predictions of the tissue maps in the test cases.

The DL-spectral CT challenge targets a specific formulation of a dual-energy CT inverse problem that has not been addressed in the literature before. The leading results show highly accurate tissue map predictions that provide evidence that the specific inverse problem of the challenge can be solved by the developed methods. We do, however, point out that theoretical proof of the inverse problem solution seems unlikely, as has been the case in inverse problems for tomographic imaging in the past couple of decades. This leaves empirical computer simulation studies as the only option to explore this or related inverse problem solutions. Thus, we look forward

to the detailed exposition of the developed algorithms and their future investigation under various formulations of the spectral CT inverse problem.

ACKNOWLEDGMENTS

We acknowledge the tremendous assistance provided by the AAPM Working Group on Grand Challenges (WGGC): Sam Armato, Kenny Cha, Karen Drukker, Keyvan Farahani, Lubomir Hadjiyski, Reshma Munbodh, Nicholas Petrick, and Emily Townley. The support from Benjamin Bearce and Jayashree Kalpathy-Cramer at the MedICI challenge platform was critical, as they implemented the challenge website and provided technical support all throughout the challenge period. We gratefully acknowledge all of the participants of the DL spectral CT challenge. This work is supported in part by NIH Grant Nos. R01-EB026282, R01-EB023968, and R21-CA263660. The contents of this article are solely the responsibility of the authors and do not necessarily represent the official views of the National Institutes of Health.

CONFLICT OF INTEREST STATEMENT

The authors declare no conflicts of interest.

DATA AVAILABILITY STATEMENT

The DL spectral CT challenge data are available at the challenge website: <https://dl-sparse-view-ct-challenge.eastus.cloudapp.azure.com/competitions/3>. To access the data, please sign up for the challenge and then follow the instructions under the “Participate” tab.

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How to cite this article: Sidky EY, Pan X. Report on the AAPM deep-learning spectral CT Grand Challenge. *Med Phys*. 2023;1-14. <https://doi.org/10.1002/mp.16363>